Minutes Session **D** – Friday 10th February 2017 – **12:18** PM

**Present members –** Jamie Izak Slome, Jack Galvin, Zehra Punjwani

**Goals**

**G1. Begin programming movement of the robot, implementing methods: moveForward(), moveBackward(), rotateLeft(), rotateRight().**

**Achievements**

**A1. Achieved first instantiation of moveForward() method by making the EV3 robot move forward a parameterized distance.**

Further comments:

*Update: Added clearer photos of EV3\_Vers\_1.0.1 showing front and side view. Gyroscope can now be seen at the centre of rotation underneath the robot.*

Following a 5-minute stand-up conversation, the entire team made clear the requirements of self-localization using the dotted line. Algorithm that finds its position to be designed by Jack and consolidated by the team for next session.

Next meeting Friday 17th February 2017. All team members should be present.